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Image Signal Processor (ISP) Drivers & How to merge one upstream

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**Embedded Linux
Conference**
North America

About me

- @ Collabora since 2016
- Mostly working on the kernel – media subsystem:
 - Maintainer of rkisp1 driver
 - Maintainer of vimc driver
- Outreachy intern in 2015 – vimc projet
- Co-coordinator of Linux Kernel project in Outreachy

Main goal of this presentation

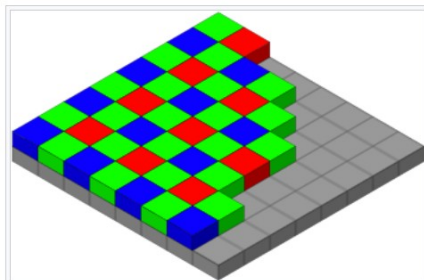
- Overview of Camera→ISP→Memory pipeline
- Overview of Media Framework
- Design choices when implementing a driver
- Lessons learned when upstreaming rkisp1 driver
- Userspace tools (libcamera)



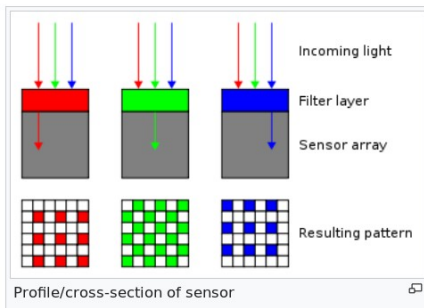


Camera→ISP→Memory

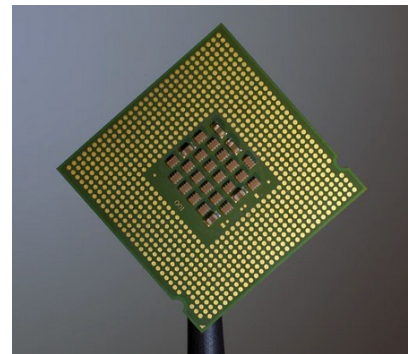
Camera sensor



The Bayer arrangement of color filters on the pixel array of an image sensor



Application



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What is an ISP?

- Image signal processor
- Common use case:
 - ISP receives the reading all those small color sensors
 - Transforms in an image usable for userspace
- Performs several other image transformations



Image Processing

- Format conversion (debayering, RGB, YUV)
- Crop / Resize
- White balance
- Compose
- Image stabilization
- Effects / filters
- Flip / Rotate
- etc

Hardware accelerated
image processing

Offloads the CPU

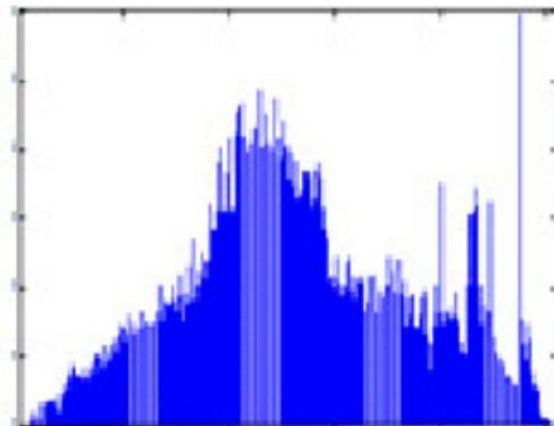


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Statistics

- ISP can generate statistics:
 - Histograms
 - Area contrast
 - etc
- Used by userspace to implement algorithms such as:
 - Histogram equalization
 - 3A (auto-focus, auto-exposure, auto-white balance)



What an ISP is not

- ISP is not a codec
- ISPs work with raw/uncompressed images
- Codecs:
 - Encoders: raw image → compressed image format (such as H.264, JPEG, VP9)
 - Decoders: compressed image → raw image





ISPs architecture

Inline vs Offline

Offline

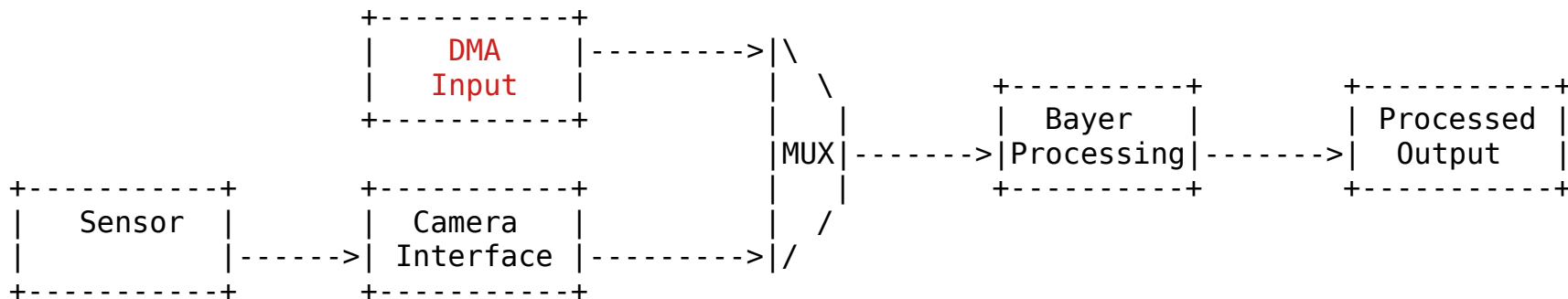
- 2 phases:
 - Sensor → Memory
 - Memory → ISP → Memory
- Usually implemented in two separate drivers
 - Coordinated by userspace
 - Example Intel IPU3:
 - IPU3 CIO2 (camera interface) driver: gets the image from the sensor
 - IPU3 ImgU driver: process this image and sends to userspace

Inline

- Data reaches memory only in the end:
 - Sensor → ISP → Memory
- Example: rkisp1 driver

Hybrid

- Can get the image directly from the sensor or from memory
- Can behave as inline, or perform the second phase of offline
- Ex: MT8183 P1





MIPI DPHY (quick overview)

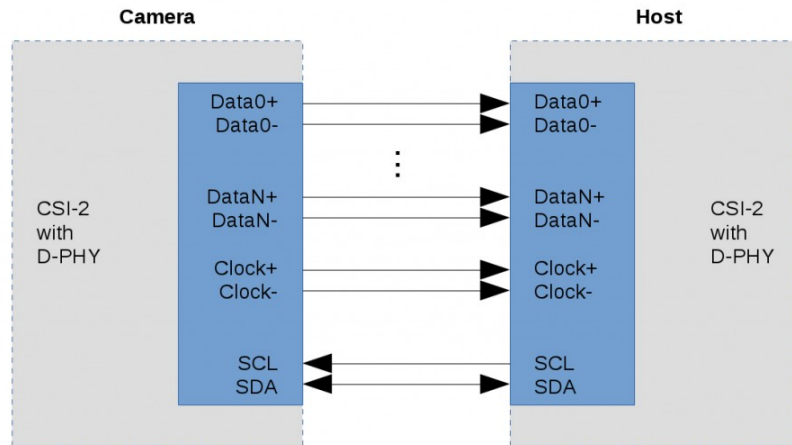
Bus – MIPI DPHY

- Very common bus used in the market for cameras and displays
- Specified by MIPI Alliance
- Physical layer with high data-rate
- 4k images with a good frame rate



Bus - MIPI DPHY

- Up to 4 data lanes
- I2C bus for configuration
- On top of this bus there can be two protocols:
 - MIPI DSI-2: Display Serial Interface, to output images
 - MIPI CSI-2: Camera Serial Interface, to capture images
- MIPI DPHY/CSI-2 → frequent term in ISP land



Study case - RKISP1

Rockchip RK3399 ISP

- rkisp1 is the driver of the ISP block present in Rockchip RK3399 SoCs
- RK3399 SoC can be found in devices such as:
 - Scarlet Chromebooks
 - RockPi boards
 - Pinebook Pro laptops



Rockchip RK3399 ISP

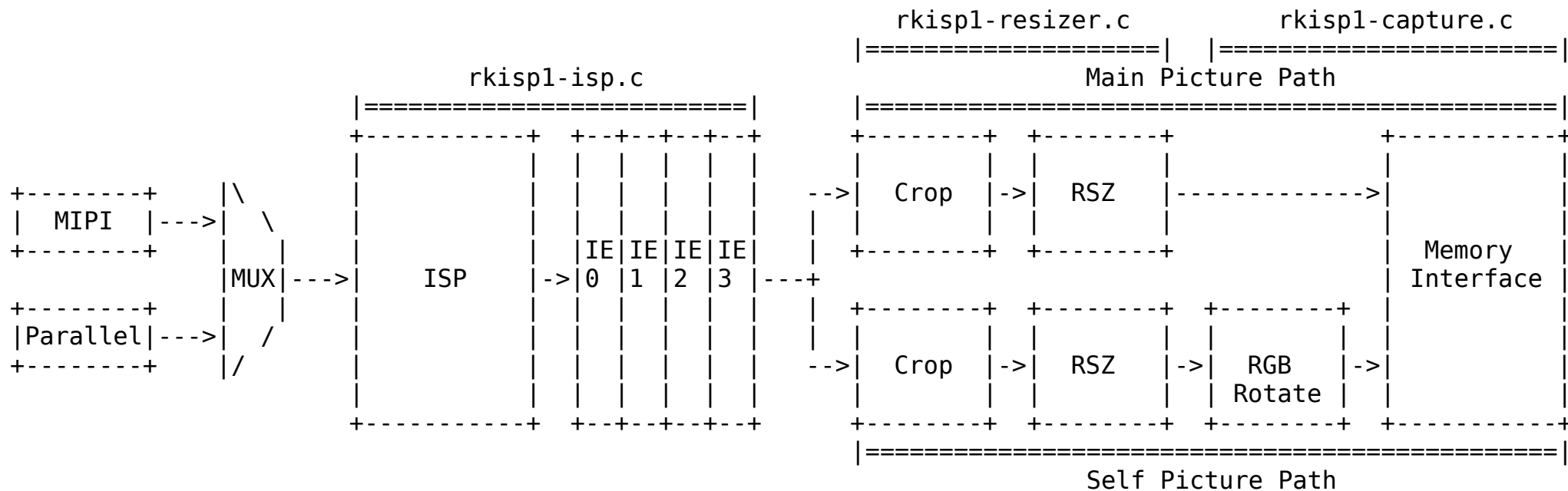
- Originally written by Rockchip
- Merged in kernel 5.6
- drivers/staging/
- 9k+ lines of code



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Rkisp1 hw architecture



Rkisp1 hw architecture

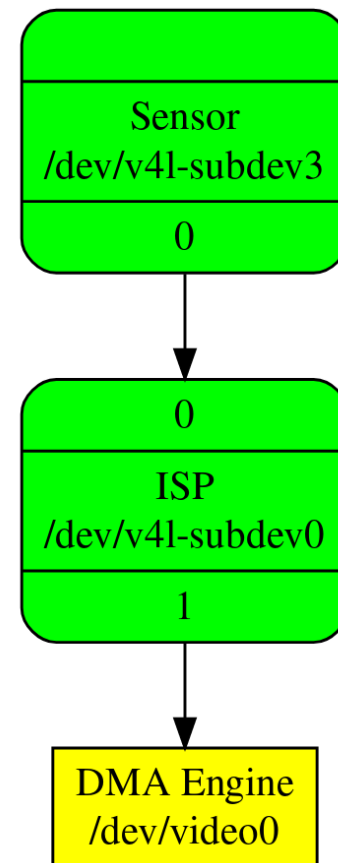
- ISP Comprises with:
 - Image Signal Processing
 - Many Image Enhancement Blocks
 - Crop
 - Resizer
 - RBG display ready image
 - Image Rotation
- Self-path: preview
- Main-path: picture



Kernel media framework

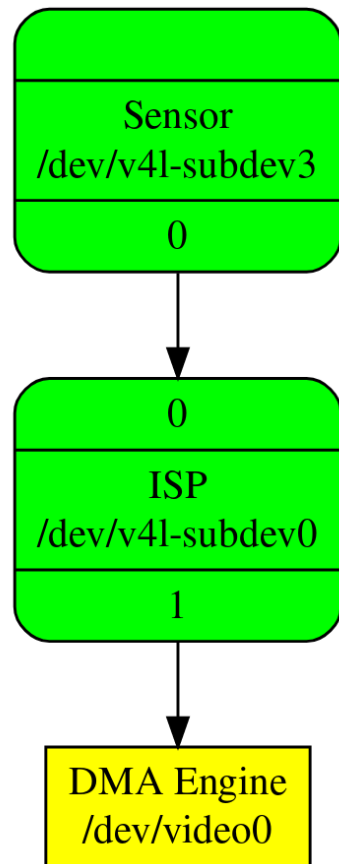
Media topology

- Linux kernel exposes a topology to userspace
- Userspace can query /dev/mediaX
 - Retrieve how inner blocks are interconnected
 - Order of image processing

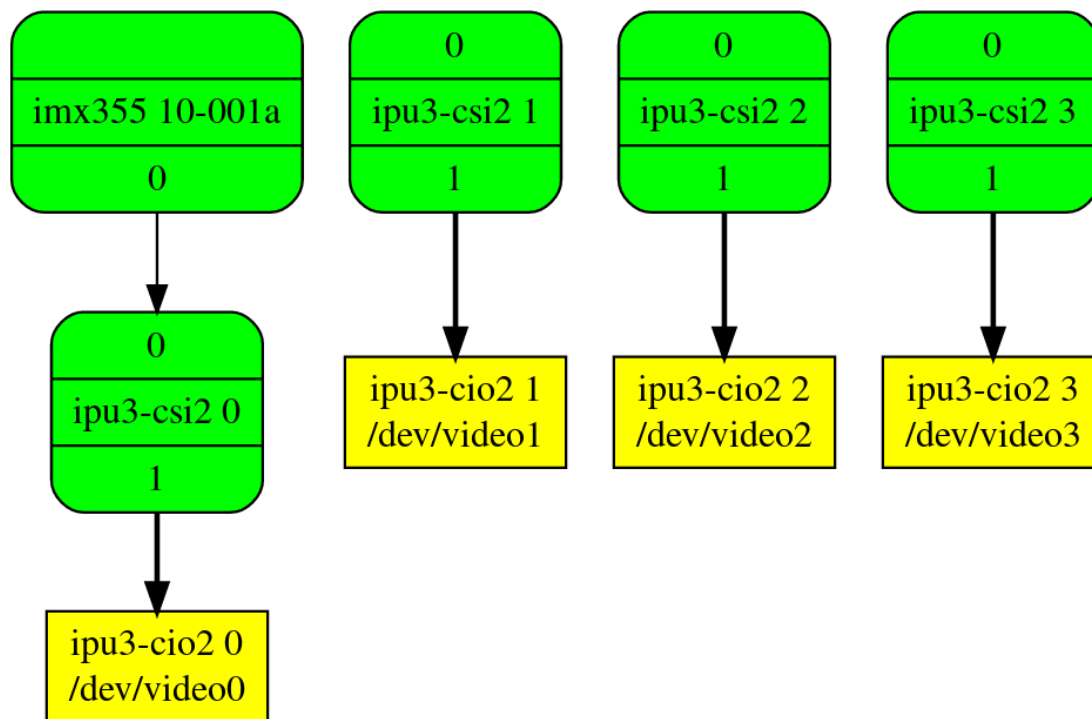


Media topology

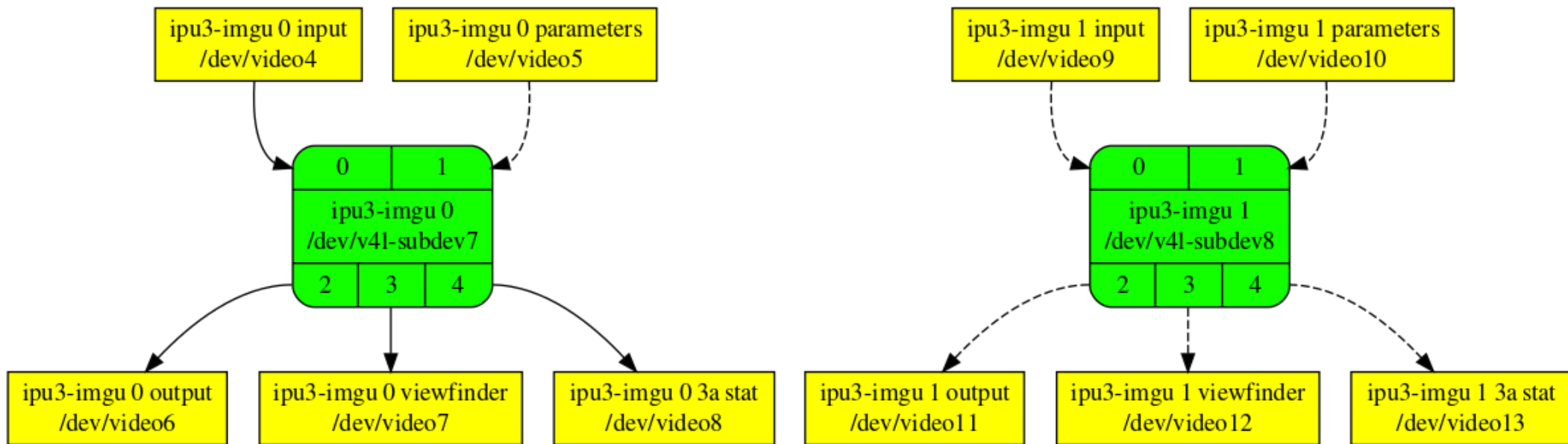
- Two types of nodes:
 - **subdevices**: inner parts of the hardware
 - **video devices**: dma engine, where userspace queues and dequeues buffers, containing images or metadata to/from the hardware
- Connected by links between pads
- NOTE: sensor is usually a separated driver



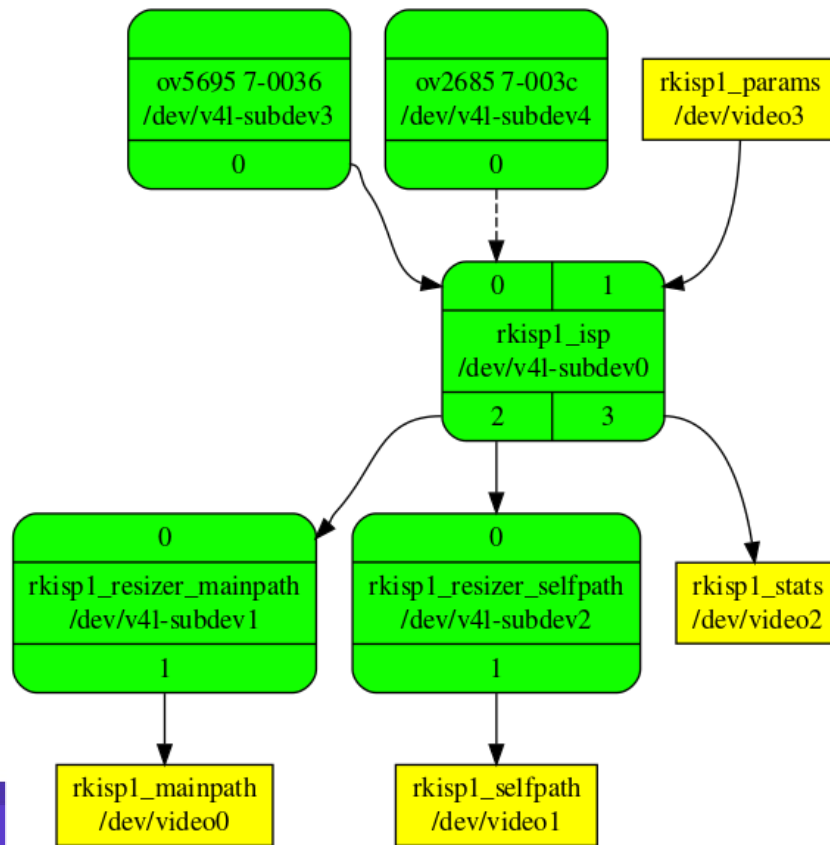
IPU3 CIO2 – offline – 1st phase



IPU3 ImgU – offline – 2nd phase



RKISP1 - inline

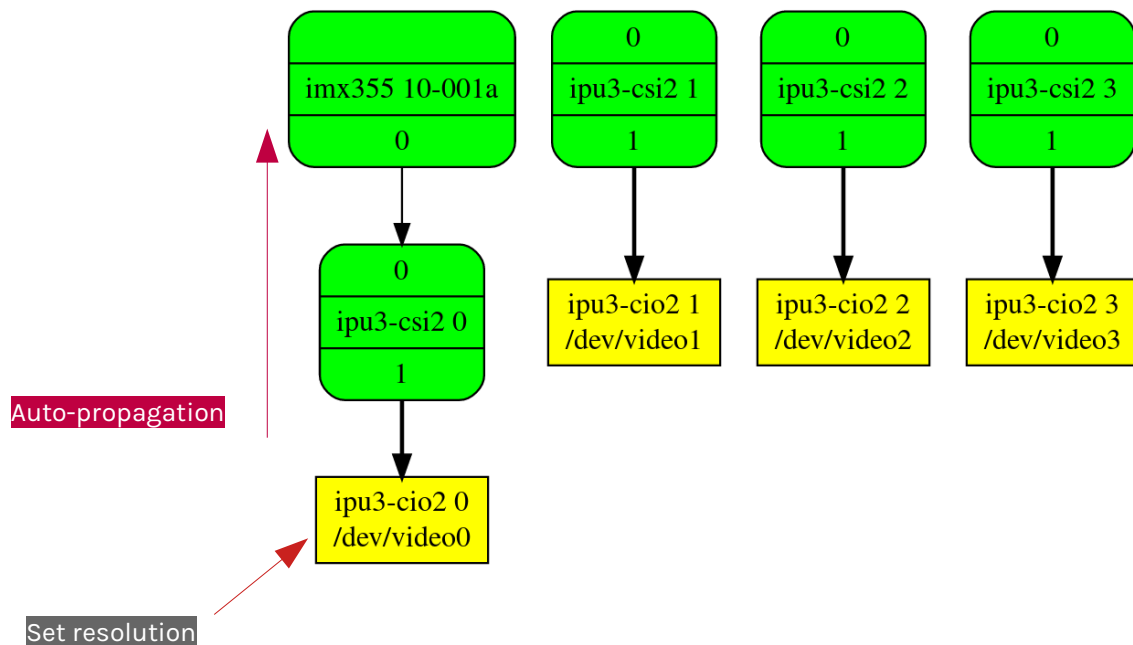




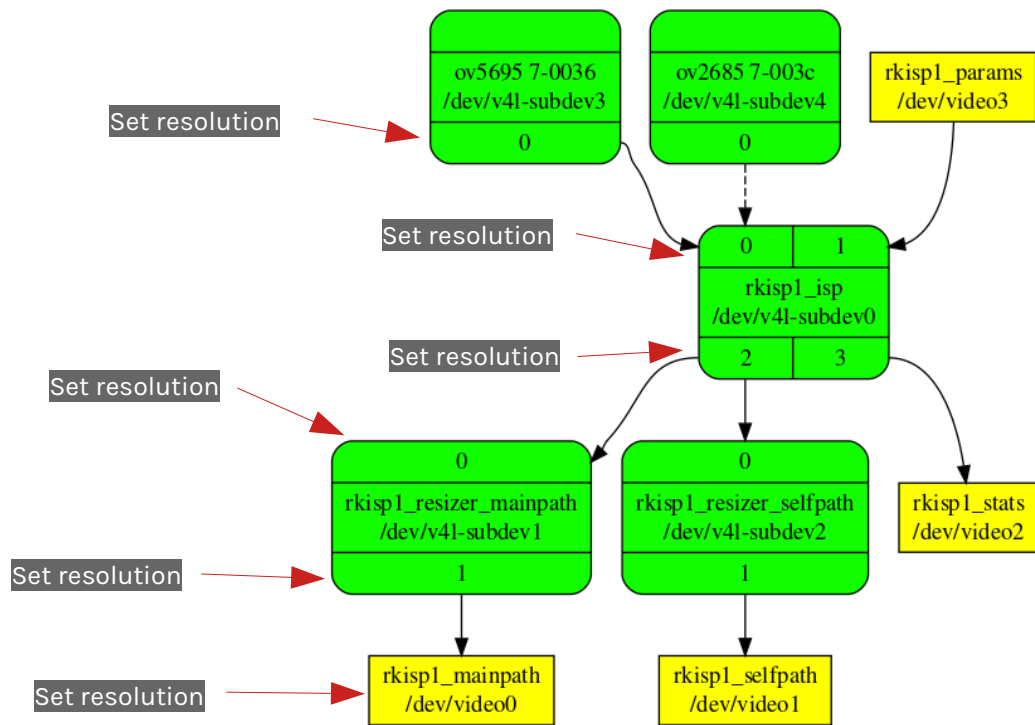
Driver config architecture

Auto vs Manual config propagation

Auto config propagation



Manual config propagation



Manual config propagation

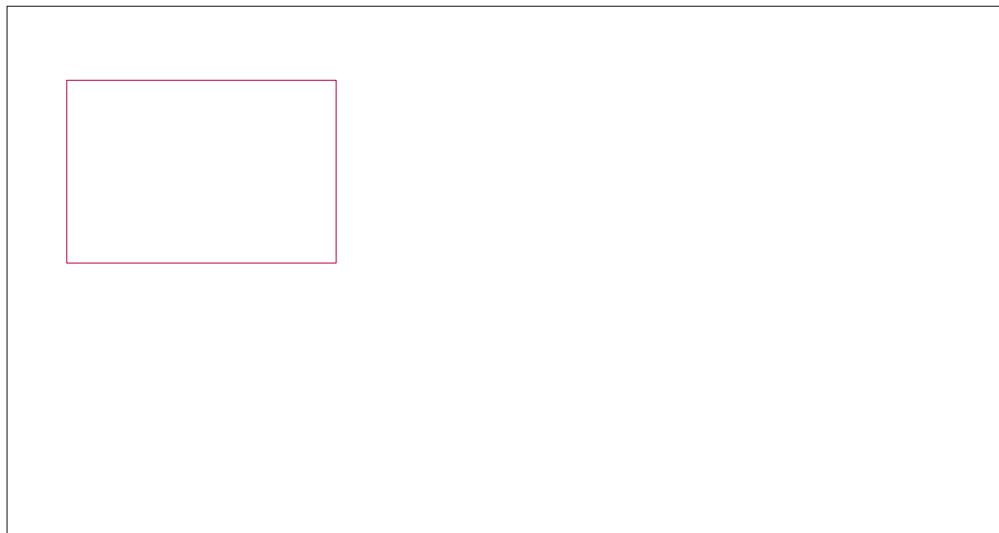
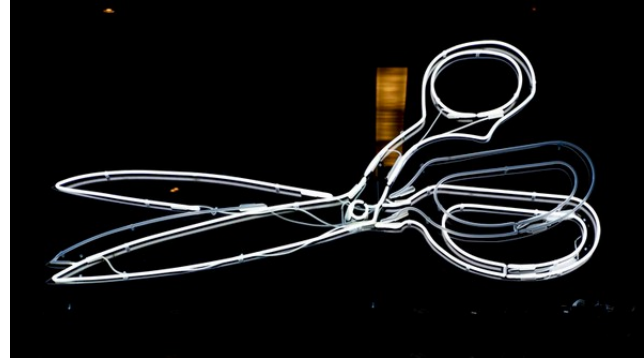
- Increases complexity for userspace
- If formats don't match → fail on STREAMON
- Finer grain configuration in inner blocks of the hardware
- More blocks exposed, more complex
- Extendable



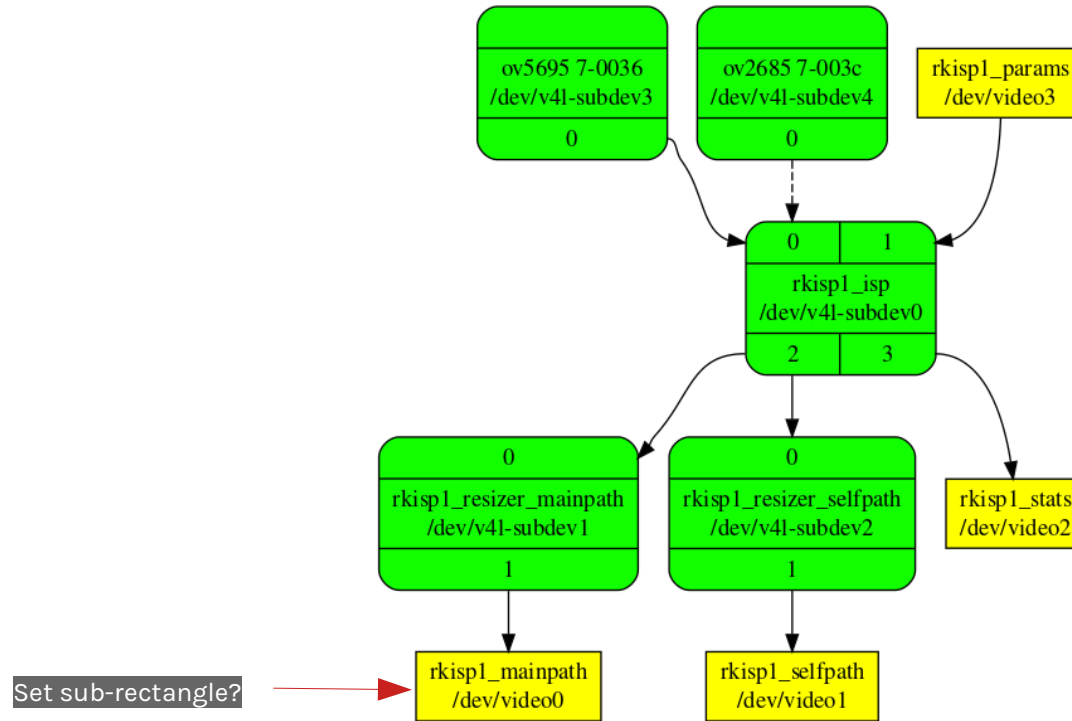
Why rkisp1 is manual?

Crop

- Specify a sub-rectangle in the image



Crop - rkisp1



Crop - rkisp1

- rkisp1 allows cropping the image from the sensor
- rkisp1 allows cropping the image before resizing
- Exposing crop once in the video node would be confusing



Crop - rkisp1

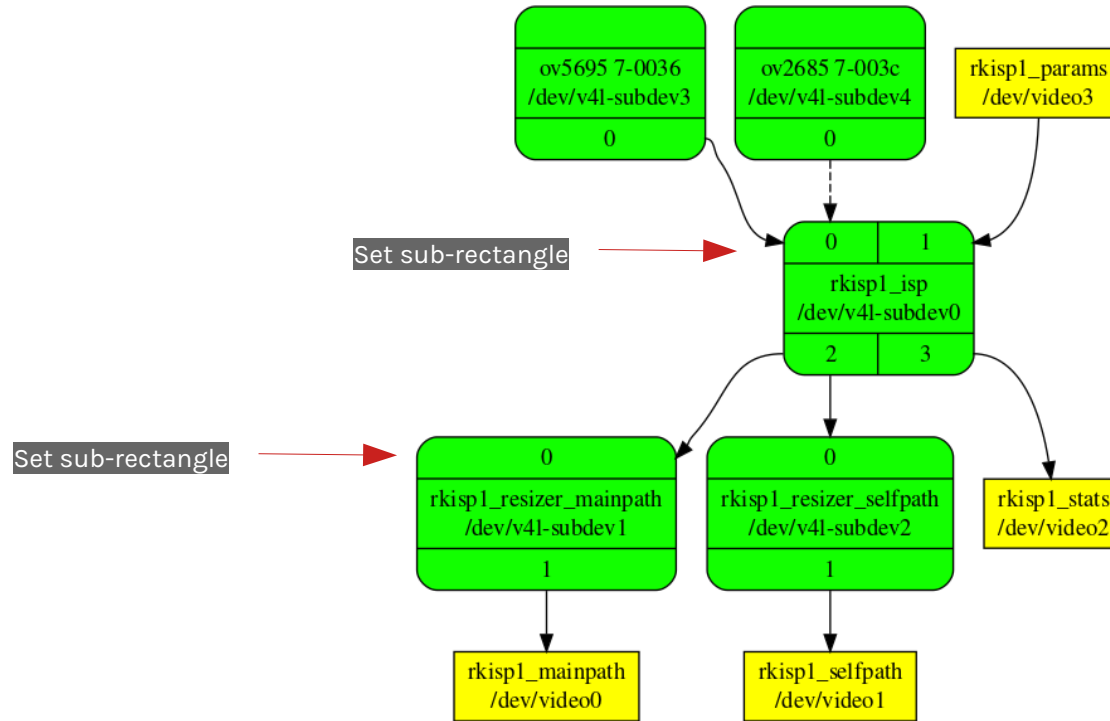
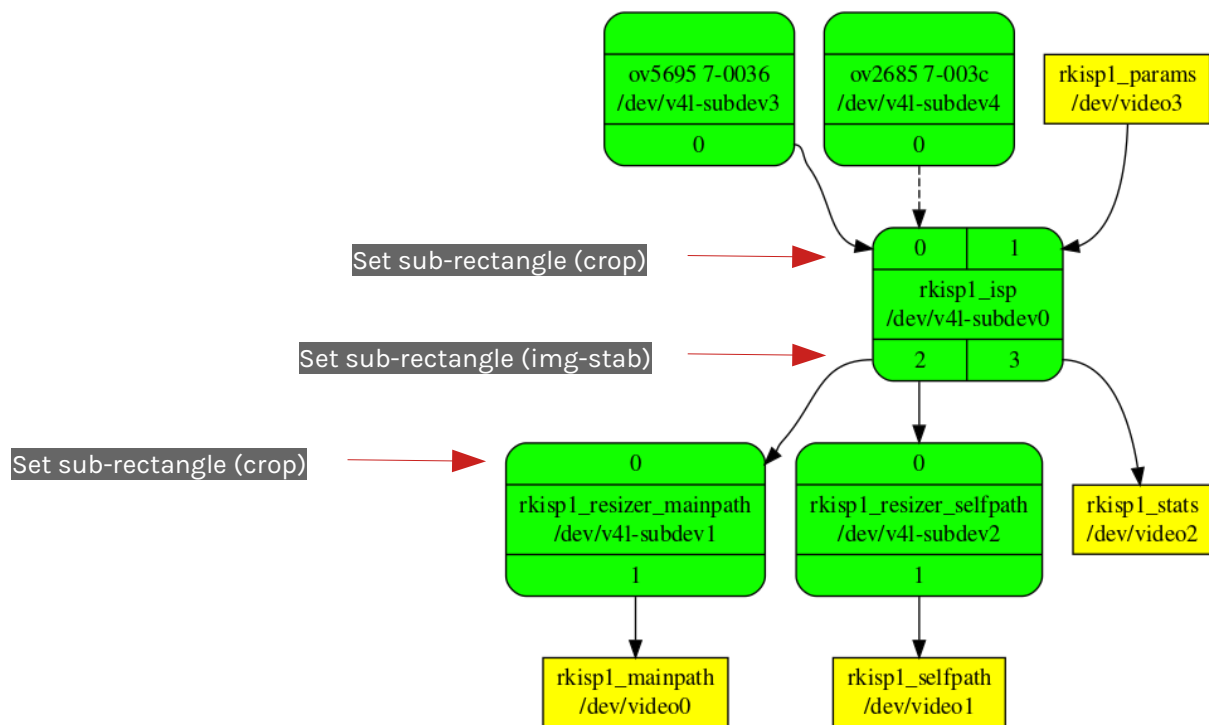


Image stabilizer

- “Lock” sub-rectangle in the picture
- Shaking the phone won’t shake the image much



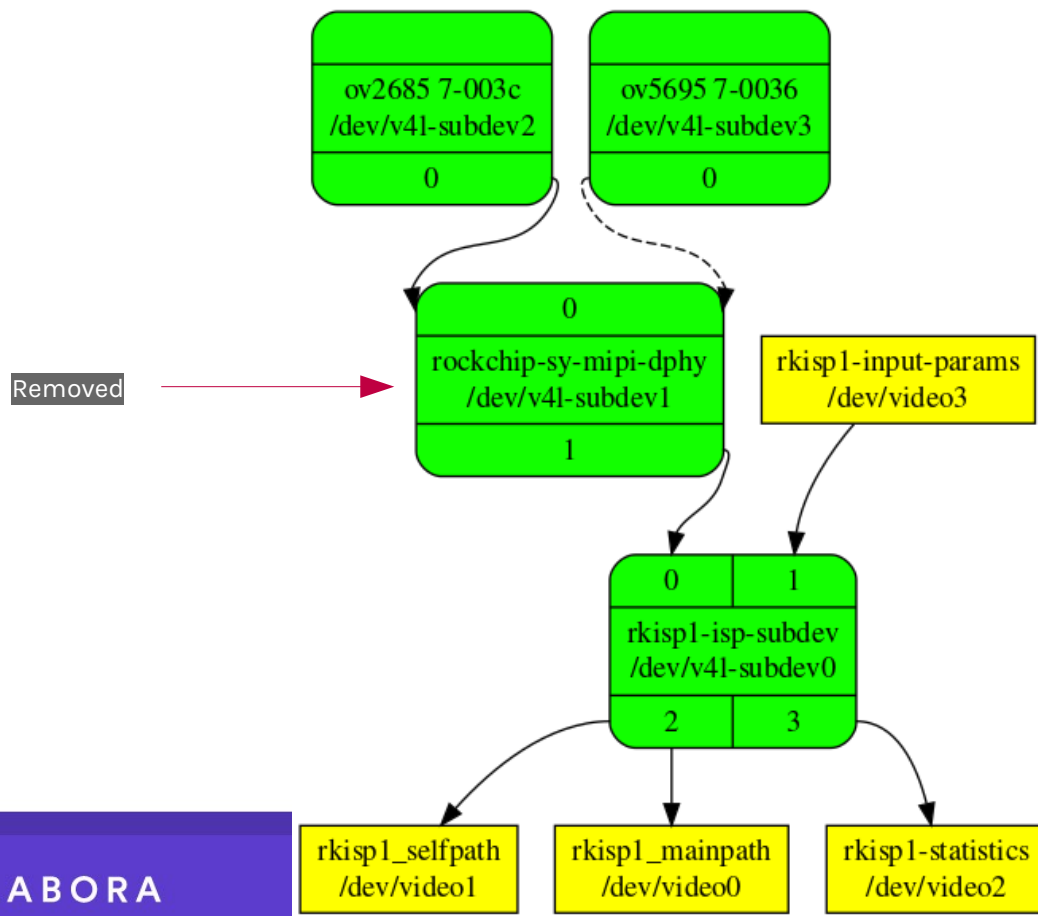
Setting sub-rectangles





Phy subsystem

Rkisp1 – original topology



Phy Abstraction Layer

- Manual config propagation → more subdevices, more complex for userspace
- Re-think exposed blocks
- Phy block → no image configuration exposed
- Topology → image processing steps
- Same processing steps can be used on top of different buses
 - ex. rkisp1: parallel (not implemented), MIPI-DPHY/CSI2

Phy – Lessons learned

- Lessons learned:
 - Migrate bus code to PHY Abstraction Layer (drivers/phy/)
 - Generic topology for any bus – less complex for userspace
 - ISP driver is much cleaner
 - Phy driver can be used for DSI



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Lessons learned

Updating to staging

- V4L2 community is open to accept drivers in staging
(with the condition that you work on it to move it out asap)
- Detailed TODO list
- Make it available to other people to use
- Improve workflow, easier to get contributions from others, testing, bug reports
- Decrease maintenance cost → no need to keep rebasing

More lessons learned

- Don't be afraid to re-organize the code (files, namings, code order, re-writing functions)
- Split the code between different files per implementation node, at least between video nodes and subdevice nodes
- Separate the code that configures the hardware, from the code that deals with the V4L2 API
- Remove code you are not using, you that you can't test, for example:
 - rk3288 support
 - phy driver ports (SoC has 2 MIPI-DPHY/CSI2 ports, I had was only using one)
 - Simplify the code – but keep extendable
 - Lots of macros in headers



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Userspace support

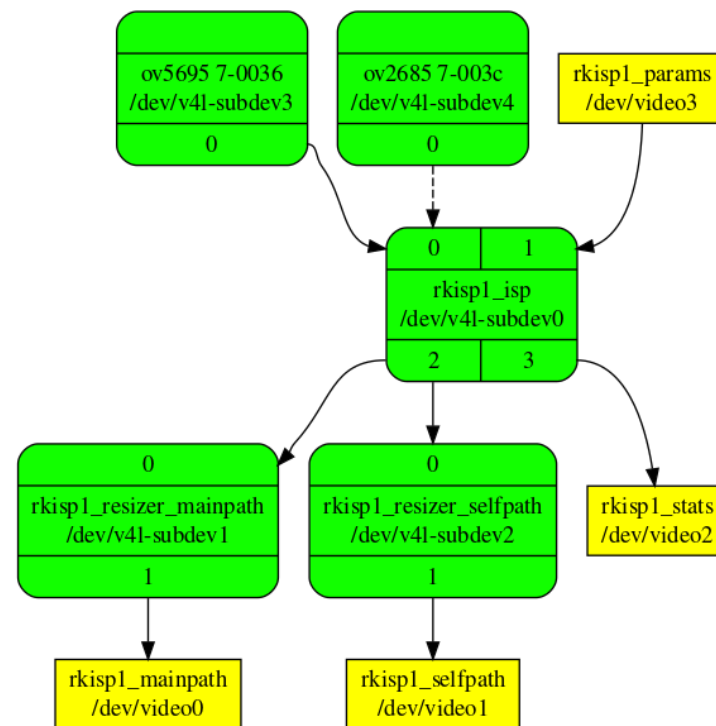
Libcamera

Complex topologies

- Not all features are auto discoverable

Examples (rkisp1):

- sub-rectangle for cropping
vs sub-rectangle for image stabilizer
- Meta-data buffers structure:
 - rkisp1_stats
 - rkisp1_params



Complex topologies

- Requires userspace specific implementation for specific drivers
- Specific applications to specific hardware
- Not very reusable code
- Hard to test

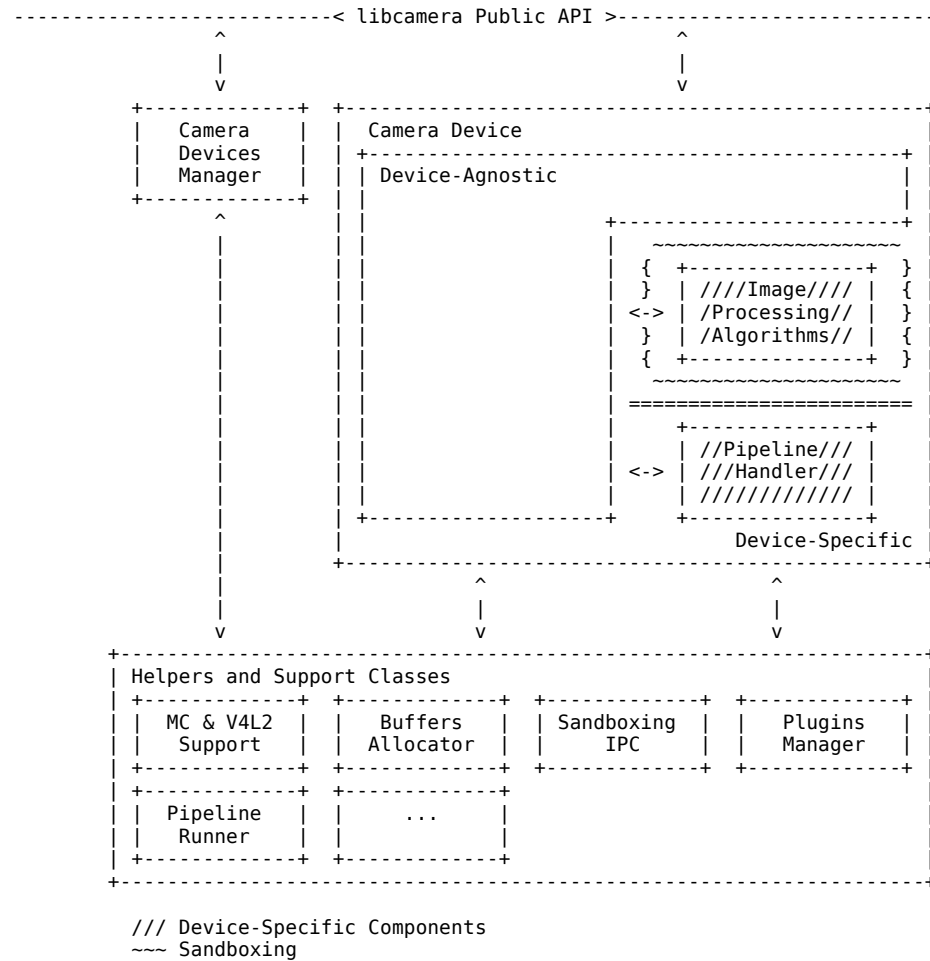


Libcamera

- Open source camera stack for many platforms with a core userspace library
- Userspace drivers
- Image processing algorithms



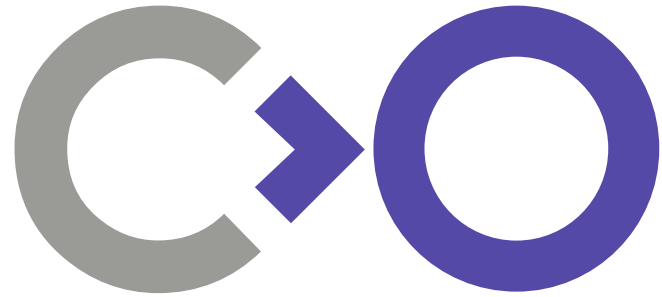
Architecture



Tips

- Add/push/update support for your hardware in Libcamera
- Easier to test
- More users
- More developers involved
- Contribute with the project





Thank you!



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